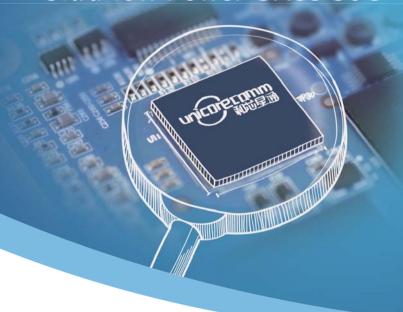


# UFirebird™ UC6226

**Ultra-low Power GNSS SoC** 



With the 28nm process and ingenious PMU design, UFirebird™(UC6226) features ultra-low power consumption and ultimate miniaturization, thus significantly improving the battery life. UC6226 is equipped with a built-in Sensor Hub which is capable of providing access for multiple sensors for fusion positioning. Through precise identification of the scene and context, it can ensure more accurate positioning experience even in the harsh signal

environment. UC6226 is developed for global application, and it supports GPS, BDS, GLONASS, Galileo, and it can achieve multiquad-system joint positioning. The high integration design reduces the quantity of peripheral devices and the board area. For QFN40 package, UFirebird complies with the AEC-Q100 reliability standard.

# **Product advantages**

- Ultra-low power consumption
- Global application, supporting GPS, BDS, GLONASS and Galileo systems as well as WAAS/QZSS/EGNOS/MSAS/GAGAN enhanced signal
- Built in Sensor Hub, leading PDR algorithm, running three system simultaneously

## **Packaging**

QFN40 5x5mm WLCSP 1.73x2.87mm

- Built-in anti-interference module, excellent adaptability to complex integrated application with 2G/3G/4G or other high frequency signals, such as mobile phones, wearables and vehicle navigation
- High integration, simple peripheral devices, and significantly reduced hardware cost.
- · One-stop location-based service
- · Compatible mainstream package
- Ultimate minaturization





# **Technical Specifications**

GNSS Performance			
Single Point	2.0m CEP	)	
Positioning			
D-GNSS	<1.0m CE	ΕP	
Time To First	Cold Star	t<29s	
Fix(TTFF)			
Velocity Accuracy	AGNSS<4	4s	
Frequency	Hot Start	<1s	
Channel	Reacquis	ition<1s	
Velocity Accuracy	0.1m/s		
Sensitivity	GPS	BDS	GLONASS
Cold Start	-147dBm	-146dBm	-146dBm
Tracking	-162dBm	-162dBm	-160dBm
Hot Start	-152dBm	-150dBm	-150dBm
Reacquisition	-157dBm	-157dBm	-157dBm

### **Electrical and Environment Feature**

	QFN	WLCSP
Power Supply	1.7V~3.6V (use DC~DC)	1.2V~1.98V
	1.2V~1.98V (bypass DC~D	(bypass DC~D0 C)
10	1.7V~1.9V; 2.8V~3.6V	1.7V~1.9V
Data updating rate	Maximum: 10F	Hz

(Required customized version)

#### Interface

Serial ports	1 UART	1 SPI Master
	1 I2C	1 SPI Slave
Ю	2 Configurable le PPS 2 external interruptinput	
	2 PIO, used for	Antenna Detect

Features	
Sensor Hub	post-processing
	Supports ten-axis sensor input
	(acceleration, gyroscope,
	magnetometer, barometer)
	Supports vehicle odometer
	pulse / information input
Geo-fence	Required customized version
Hybrid	sensor and GNSS fusion
	positioning
Anti-interference	Built-in, Active anti-jamming
	signal detection and removal
LNA	Built-in
DC-DC	Built-in, optional
Data updatingrate	Maximum 10Hz
Data Format	NMEA0183, Unicore Protocol
GNSS clock input	Support TCXO or Crystal
RTC Input	32.768kHz optional (Frequency
	can be divided by GNSS clock)
Storage	Built-in ROM firmware, support
	external SPI Flash and AP SPI

#### **Environment**

oprating: -40°C~+85°C	
storage: -50°C~+125°C	
MSL3	
Complaint	
Optional, support	
QFN 40 packaging	

firmware